

# **GMD128**

## **Morrow MD128 Z80 Computer Emulator.**

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4th December 2020

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# 1. INTRODUCTORY INFORMATION

## 1.1 Overview

GMD128 emulates the early 1980s Morrow Micro Decisions Z80 Computer Series.

GMD128 uses disk-image files which may contain Morrow MDxx Operating Systems of the period: mainly CP/M. Other Morrow Operating Systems may work, but haven't been tested.

Most of the Morrow Micro Decision systems used either two floppy disks or one floppy disk plus one hard disk. The size of the hard drive generally indicated the name of the system. Thus, the Morrow MD11 system had a floppy disk plus an 11-megabyte hard disk. There was no such animal as a Morrow MD 128. If it had existed, it probably would have cost in the vicinity of \$50,000 – an absolute fortune in the mid 1980s. I have used that name to indicate that it has 128 megabytes of hard disk storage. This is made up of four 32 megabyte hard drive image-files, each of which holds four 8-megabyte CP/M virtual disk drives.

GMD128 is constructed from two modules. The first module, the GXE Z80 Emulator Toolkit, contains the 64K of RAM, a Z80 microprocessor emulator, and a display screen. Drop-down menus emulate the operator's interaction with the hardware, such as inserting or removing floppy disks, and organizing the interaction between the host linux machine and the virtual Z80 machine. This first module is installed as a Graphical User Interface (GUI) and can be called by GMD128 or any other Z80-based emulator software, such as CPZ (ICMS CPZ-48000 emulator) or NSE (North Star HORIZON emulator).

The second module consists of the Morrow system-specific components, such as the data and control ports of the serial and parallel I/O, the Disk Jockey DMA floppy-disk controllers, with associated boot PROMS, and the HDDMA fixed-disk controllers

## 1.2 ATTRIBUTIONS FOR OTHERS' CODE in GMD128

GMD128's Z80 emulation code pretty much comes from yaze, a CP/M emulator written by Frank Cringle. Morrow-specific code amendments such as the floppy-disk I/O, and a few other additions such as Mode 2 interrupt code were made by Jack Strangio.

GMD128's Z80 disassembly code comes from Marat Fayzullin's 1999 DAsm code with some local alterations.

The rest of GMD128 cannot be blamed on anyone else but myself.  
Jack Strangio, November 2020

### 1.3 THANKS

I have only the greatest appreciation for all those who have helped me in my rather idiosyncratic quest to write emulators of the North Star Horizon, and several other 'home computers' as they were called in the late 1970s and early 1980s.

The North Star Horizon was my first computer which took more than 40 hours to build over the course of several weeks in late 1978. The thousands of solder-joints literally burned-out a new soldering iron. It says a lot for the quality of the instruction manual that most of the time I really had no idea what each step did but at the end (once my half-dozen wiring mistakes were fixed) I had assembled a computer which worked perfectly.

Often, just a little bug in the emulators would get people off writing to me and setting off another round of debugging and coding. Thanks to you all.

### 1.4 FLOPPY DISKS AND FOUR HARD DISKS SUPPLIED WITH GMD128

Several floppy disks are supplied with GMD128 to get you up and going quickly. They are stored in the 'disks' subdirectory. These archive disks have been renamed to allow their uses to be self-explanatory.

#### **boot-8hx-b114.fd8**

8-inch boot disk (8hx) The BIOS version B114 is configured for 2 8-inch floppies A: and B: and two of the JX32 hard drives (C:,D:,E:,F: and G:, H:, I:, J:).

#### **empty-8hx.fd8**

8-inch blank floppy disk.

#### **jx32\_abcd.img**

32-megabyte hard drive with boot system track. (hxx) This BIOS B113 is configured for zero floppy disks, and four 8-megabyte hard drives, giving the maximum number of sixteen CP/M disk drives. The size of each CP/M virtual disk, 8-megabytes, is the maximum size allowed by CP/M.

#### **jx32-efgh.img**

#### **jx32\_ijkl.img**

#### **jx32\_mnop.img**

32-megabyte data drives.

Some of the data drives have been used for development, especially the B: drive which has several GMD128 BIOS source files.

### 1.5 SCREENSHOTS

*(Note: Most of the screen images included in this User Guide do not render well. They look better when displayed dot-for-dot as screenshots. Find them in the 'screenshots' directory of the downloaded tarball.)*

GMD128 is GTK+ based. When GMD128 starts up it will look at the screen-resolution and display a 'terminal' of a size that is suitable for that resolution. The 'large' terminal (110 chars wide, 45 lines) will fit on a 1920x1080 screen. The 'medium' terminal (96 chars wide, 36 lines) will fit on an intermediate resolution laptop. Then there is the 'small' terminal which is actually the historical standard-sized serial terminal of 80 chars wide and 25 lines high. Both the medium and small terminal displays can be specified with a command-line option.

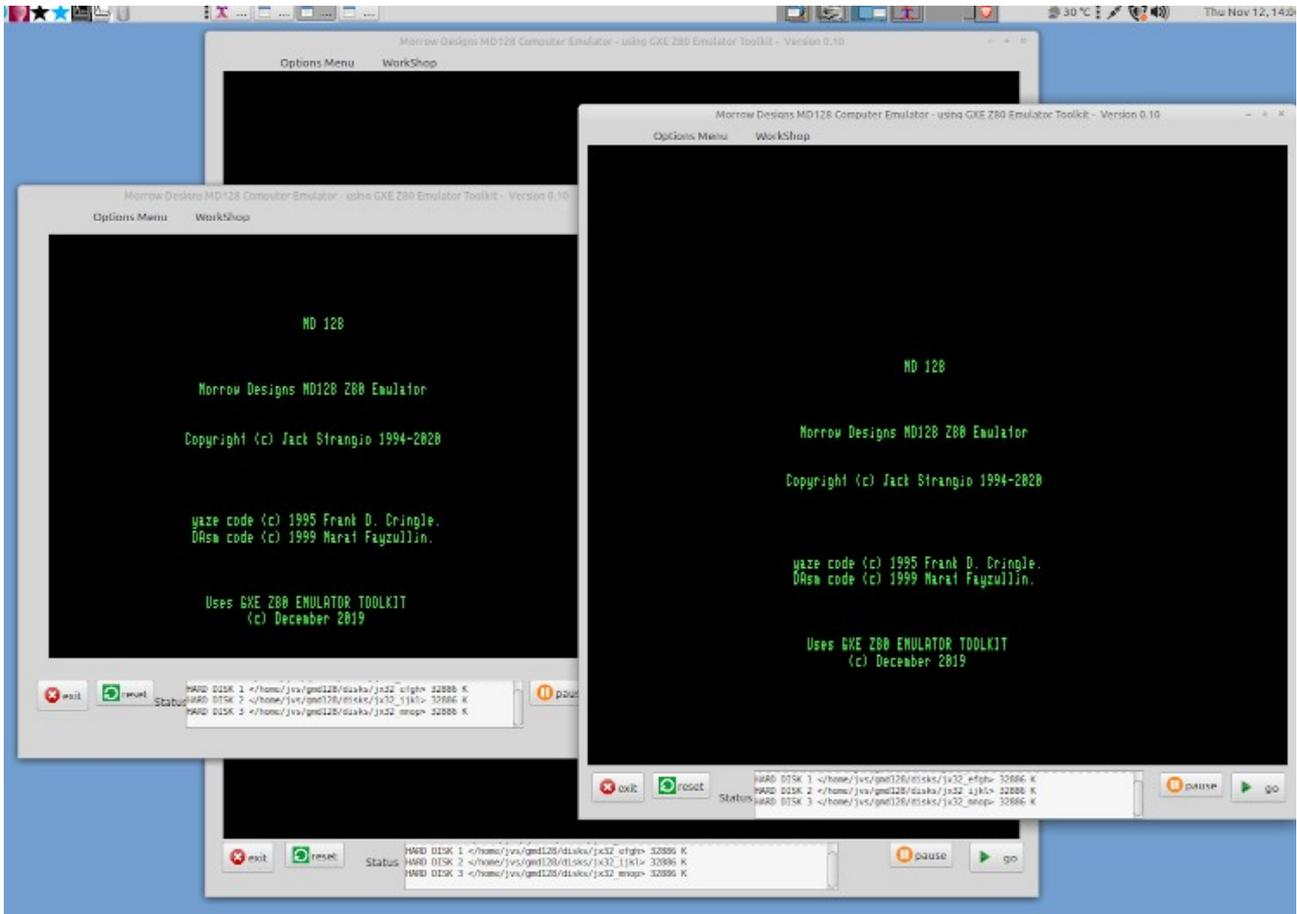


Fig 1. Three GMD128 startup screens, running on a 1920x1080 resolution screen in 110x45 display, 96x36 display, and in 80x25 character screen formats.

```

MORROW DESIGNS 64K CP/M ver. 113HXX
ABCDEFGHIJKLMNPO: HDC/DMA (4x JX32)

A>XDIR

File Typ Size File Typ Size File Typ Size File Typ Size
-----
++VDISK+AAA 0K : ASM COM 8K : CORTESI LIB 8K : CP COM 12K
CPM2UNIXCOM 4K : DDT COM 8K : ERAQ COM 4K : FILLDISKC 4K
JX32-FMTASM 16K : JX32-FMTCOM 4K : LAST COM 0K : LMS COM 16K
MAC COM 12K : NEWMAC LIB 28K : PIP COM 8K : SERIALZ ASM 8K
SERIALZ COM 4K : STAT COM 8K : UNARC COM 8K : UNERA COM 4K
UNIX2CPMCOM 4K : WINSTALLCOM 32K : WS COM 16K : WS INS 60K
WSL COM 16K : WSMGS OVR 28K : WSOVLY1 OVR 36K : WSOVLY10OVR 36K
WSU COM 20K : XDIR COM 4K : Z80 LIB 8K : Z80J LIB 12K

[ User 0 ] 32 Files Using 436 Kbytes of a 8128 Kbyte Drive
989 Directory Entries, with 7724 Kbytes Remaining on drive A:
A>

```

Fig 2. GMD128 splash screen followed by CP/M directory listing. GMD128 looks like a typical "green-screen" terminal of the 70's-80's period, in particular it will default to be a terminal which acts very similar to Televideo 920/ Soroc 120/ ADM3A terminals.

```

Options Menu      workshop
A:JX32-FMT.ASM  FC=915 FL=24 COL 27      INSERT ON
;JX32-FMT.ASM
;
;UTILITY FOR FORMATTING JX-32 HARD DISK IMAGE-FILES FOR USE WITH MORROW
;MICRO-DECISION HARD DRIVE CONTROLLER, HOCDMA. THE JX32 HARD-DRIVE
;IMAGE-FILES CONTAIN FOUR 8-MEGABYTE CP/M DRIVES. USING FOUR OF THESE
;HARD-DRIVES GIVES THE COMPLETE COMPLEMENT POSSIBLE OF 16 CPM/DRIVES,
;DRIVE A: THROUGH TO DRIVE P:, EACH WITH 8 MEGABYTES OF DRIVE SPACE.
; jvs 200912
;
;          MACLIB  Z80
;          ORG 0100H
;
;BGIN     JMP     BGIN2
;
;          DB      'FORMATS JX32 HARD DRIVE IMAGEFILES'
;
;          ORG 0120H
;cmds    DB      00H,01H,02H,03H,04H,05H,06H,07H,08H,09H,0AH,0BH,0CH,0DH,0EH,0FH
;-----
;cmds    DB      13H,61H,02H,03H,00H,00H,00H,00H,00H,00H,00H,06H,00H,30H,01H,00H
;XCMD    DB      03H,00H,00H,03H,00H,00H,00H,00H,00H,00H,00H,06H,00H,30H,01H,00H
;
;          ORG 0150H
;
;BGIN2    CALL    MKSECTOR      ;SET UP 1K SECTOR BUFFER
;
;          LXI    SP, CMDS      ;PUT STACK BELOW HOCDMA CMDS
;          LXI    D, BANNER
;          MVI    C, 9
;          CALL   BDOS
;
;BGIN3    LXI    D, DSELECT     ;'SELECT DISK'
;          MVI    C, 9
;          CALL   BDOS
;
;          LXI    D, INLINE     ;GET INPUT STRING ANSWER
;          MVI    C, 10
;          CALL   BDOS
;
;          LDA    INLINE+1      ;PROCESS ANSWER
;          LDA    INLINE+2
;          CPI    'X'
;          JZ     ABORT

```

Fig 3. A custom-configured version of Word Star running in a high and wide screen format (110 chars,45 lines)

## 1.6 GMD128 COMMAND-LINE START-UP OPTIONS

**gmd128 [-c config-file] [-m or -l]**

**-c <config-file>**

Use an alternate config-file instead of the default '/home/username/gmd128/gmd128.conf' file. The alternate file should also be placed in the '/home/username/gmd128' directory.

**-m**

Specify the use of a display 96 characters wide by 36 lines.

**-l**

Specify the use of a display 110 characters wide by 45 lines.

## 1.7 GMD128 COMMAND-LINE STARTUP EXAMPLES:

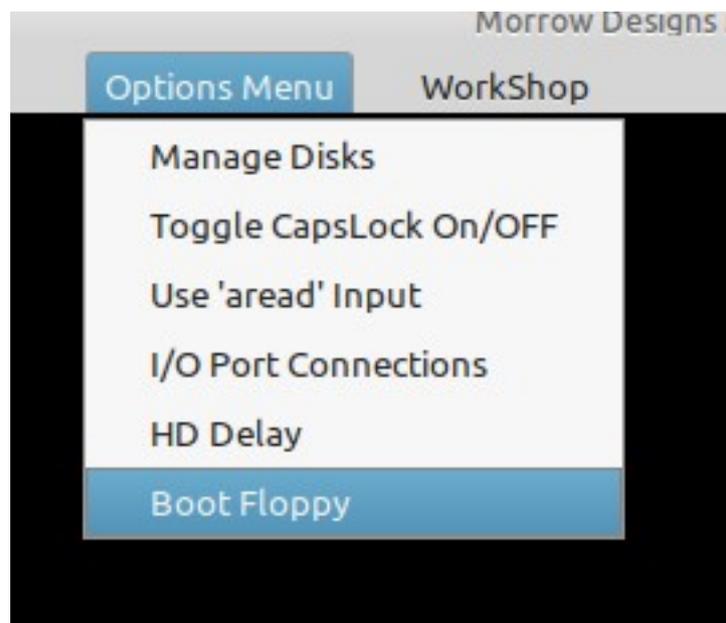
**gmd128 -c morrow.zzz**

Start GMD128 using the floppy or hard disk controller, booting from the disk-image file which is specified in the '/home/username/gmd128/morrow.zzz' configuration file.

**gmd128**

Start GMD128 using the floppy or hard disk controller, booting from the disk-image specified in the default configuration file.

*NOTE: The default boot device is the hard drive. To boot the with the floppy disk, open the Options Menu, and toggle the 'Boot Floppy' menu item to 'ON'. The emulator will boot from the floppy the next time the emulator is started or reset. To go back to booting from the hard drive again, toggle the 'Boot Floppy' menu item to 'OFF'.*



## 1.8 GETTING THE EMULATOR'S START-UP CONFIGURATION

### 1.8 THE WORK DIRECTORY

All of the emulators do their work in a directory which has the general look of

```
/home/user_name/emulator_name/
```

thus if user 'fred' is working with the 'gmd128' emulator, the gmd128 work-directory is installed at

```
/home/fred/gmd128
```

In this work-directory will be found any logfiles, such as the **screenlog** which contains a record of all the output that was displayed by the screen during the emulator's activity. If any debug logging was required there will be a debug log called **xlog** written into the work-directory.

Also found in the work-directory are any configuration files which specify which floppy and hard disk images will be used while the emulator is working.

Subdirectories in the work directory are **disks**, **documentation**, and **info**.

The **disks** subdirectory is where floppy and hard disk images may be found. It is a good idea to put any other disk-images in there also. That is the first place that the emulator will usually look for disks.

The **documentation** subdirectory is where official Manufacturer and CP/M documentation is found.

The **info** subdirectory is where other useful information may be placed.

### 1.9 CONFIGURATION FILES:

A user's default configuration file is found at

```
/home/username/work_directory/emulator_name.conf
```

thus user **fred** will find his *default* **gmd128** configuration file at

```
/home/fred/gmd128/gmd128.conf
```

Bear in mind, though, that any other configuration filename can be specified on the command-line by using the **-c** option, as in

```
/home/fred/.local/bin/gmd128 -c gmd128-001.conf
```

or even just simply

```
gmd128 -c gmd128-001.conf
```

if gmd128 is located in one of your \$PATH directories, and gmd128-001.conf is located in the work-directory.

## 1.10 USER CONFIGURATION FILES: gmd128.conf

This is an actual configuration file.

```
###
### Configuration File for Morrow GMD128 Z80 Emulator (c) 201112
###
###           Avoid Editing This File Manually.
###
### Any Changes You Make Are Liable To Be Overwritten at Any Time.
###
fd0           /home/jvs/gmd128/disks/empty-8hx.fd8
fd1
fd2
fd3
hdd0          /home/jvs/gmd128/disks/jx32_abcd.img
hdd1          /home/jvs/gmd128/disks/jx32_efgh.img
hdd2          /home/jvs/gmd128/disks/jx32_ijkl.img
hdd3          /home/jvs/gmd128/disks/jx32_mnop.img
disk_dir      /home/jvs/gmd128/disks/
hd_delay      off
capslock      on
s2_in         /home/jvs/gmd128/serial2_in
s2_out        /home/jvs/gmd128/serial2_out
pl_in         /home/jvs/gmd128/parallel_in
pl_out        /home/jvs/gmd128/parallel_out
=====
log           /home/jvs/gmd128/xlog
screenlog     /home/jvs/gmd128/screenlog
debug_level   0013
break_addr    FF00
break_on      off
trap_addr     FFFE
trap_on       off
boot_floppy   off
```

Note that although there is provision for 4 floppies and four hard drives, this config file only specifies 1 floppy and four hard drives. The hard drives named each hold 4 quite large (8 megabyte) virtual disks out of the 16 CP/M drives possible.

The **disk\_dir** indicates where the last disk used was located, and where the emulator will look first for any other disks that are wanted.

The **hd\_delay** is a way of slowing down the emulator's hard drive, usually during emulator development. Apart from that situation, the **hd\_delay** can be left off as the normal case. See section XX for adjusting this.

**Capslock** is as described. Most people using CP/M will want the capslock on, but won't want it 'on' for their host machine. See section XX to vary the condition.

All the items under the ===== separator are normally used only during the development of the emulator itself and so will rarely be used (if ever) by most **gmd128** emulator users.

NOTE: While it is possible to edit the configuration file manually, your changes will be overwritten when any of the 'Options Menu' or 'WorkShop' menu items are used.

## 2. Obtaining and Building 'GMD128'

### 2.1 Linux Libraries required

Very few Linux libraries are required, apart from the standard packages installed on most Linux Distros.

The GUI Toolkit used is GTK+ Version 3, apart from a few deprecated functions from GTK+ Version 2.

This Toolkit can be installed using your Package Manager. If you're using one of the Debian derivatives such as Debian itself, Mint, or Ubuntu, this can be done by installing **libgtk-3-dev** and **libglib2.0-dev** using Synaptic or even just

```
sudo apt install libgtk-3-dev libglib2.0-dev
```

from the command line.

### 2.2 Get the source files

Download the GMD128 source code from [https://itelsoft.com.au/code/gmd128\\_gtk\\_latest.tar.gz](https://itelsoft.com.au/code/gmd128_gtk_latest.tar.gz) and move it to any convenient work directory. Untar and decompress the tarfile:

```
tar xvfz gmd128_gtk_latest.tar.gz
```

This will produce a subdirectory called gmd128. Move there.

```
cd gmd128
```

Compilation should be initiated with a simple **make** on the command-line.

If all goes well and the compile completes successfully, install the gmd128 package with

```
make install
```

This will install the package in the **/home/username/gmd128** work directory. So user 'fred' will find a directory called **/home/fred/gmd128**.

A launcher icon will appear on the username's Desktop. Clicking on that should launch the emulator. It can be 'Drag n Dropped' to the Desktop Panel with most Desktops. Alternatively, GMD128 can be invoked from the command-line if the **gmd128** executable file is to be found somewhere within your \$PATH list.

```
gmd128
```

### 2.3 What's in the /home/username/gmd128 work-directory?

The /home/username/advantage directory has several important files:

**gmd128.conf**            the default configuration file for GMD128 which holds most of your personal preferences and:

- designates which CP/M disk image-files are mounted.
- specifies what I/O files will be attached to the machine's I/O ports.
- preferred settings for capslock, hard-drive 'speed'.
- preferred gmd128-development settings.

Avoid editing the gmd128.conf file manually. It gets updated automatically every time you make different choices on the Options and WorkShop menus, and will hold those settings indefinitely over more than one session.

**pio\_out**                destination of text from the parallel-out port: the 'LST:' device in CP/M

**sio\_out**                destination of text from the serial-out port: the 'PUN:' device in CP/M

## 2.4 Starting up GMD128

Starting GMD128 can be done from the Desktop with one of the emulator icons or from the command-line. On start-up, the program will show the title (splash screen) and will then wait for user input. Usually, the user will then just hit the 'go' button because the installation process also provides the default configuration file, **gmd128.conf**, which will be found in the GMD128 work directory, **/home/username/gmd128**

gmd128.conf contains the default settings which are expected by the Morrow Micro Decision 128 computer:

A boot floppy *must* be in 'floppy drive' 1 at the minimum when booting from the floppy.

Several GMD128 settings are also stored in the gmd128.conf file. Such as Capslock ON/OFF, and whether the hard drives runs FAST or SLOW. The **gmd128.conf** file should not be edited manually. While that can actually be done, any changes you make may not be permanent.

If for some reason, the default configuration is not present in the top directory, then a new configuration file needs to be made. This is simply done by providing the user's settings with the 'Options Menu', and/or the WorkShop menu. See Section 3, page 18. Any time a setting is altered with these two menus, the new setting is saved automatically into the **/home/username/gmd128/gmd128.conf** file.

'Options Menu': Things to be changed by the everyday user.

'WorkShop' menu: Settings for use during GMD128 development. Most users won't need to bother with these.

## 2.5 Running Morrow's CP/M. The 'go button.

Now hit the 'go' button. The screen will clear, followed almost immediately by the CP/M Banner

```
MORROW DESIGNS 64K CP/M ver. 113HXX
ABCDEFGHIJKLMNPO: HDC/DMA (4x JX32)
```

```
A>
```

indicating that CP/M has been loaded from the hard disk boot, with the 'A>' prompt indicating that it is waiting for a normal CP/M command-line as user input.

The BIOS version shown here has a serial number followed by 'HXX' which indicates that the BIOS has provision for

```
H: boots from JX32 hard disk
X: NO provision for 8-inch floppy drives
X: NO provision for 5-inch floppy drives
```

The BIOS version provided on the 8-inch floppy disk-image is '8HX', which indicates:

```
8: boots from 8-inch floppy disk
H: has provision for JX32 hard drives (x2)
X: NO provision for 5-inch floppy drives.
```

## 2.6. Pausing the Emulator. The 'pause' button.

In most cases you won't usually need to use the pause button unless things happen to move too fast for you, for instance to change floppies before the software moves on. Otherwise, using the Emulator is just like using a normal computer.

## 2.7 Rebooting/Resetting the Computer. The 'reset' button.

Just like the real thing, a reset will wipe the screen and reboot the emulator from scratch. Use this button sparingly, your work may be lost.

## 2.8. Finishing Up. The 'exit' button.

Pack it up and put it away. The GMD128 program closes down and the emulator window is closed. Settings in gmd128.conf will remain for next session.

## 2.9 The 'Status' window

In between the two pairs of buttons, left and right, is a small window which displays short one-line messages. This is used to show information or warnings regarding the progress of the emulator. A short beep may be heard when some messages are shown. Examples:

```
Morrow MD128 Z80 Computer is RUNNING  
Capslock is now ON  
HARD DISK 3 </home/fred/gmd128/disks/jx32_mnop.img> 32886 K  
Morrow MD128 Z80 Computer RESET. Rebooted.
```

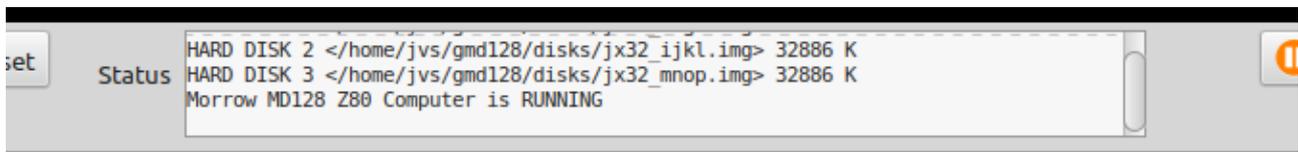


Fig 5. The Status Window

### 3.0 The Options Menu

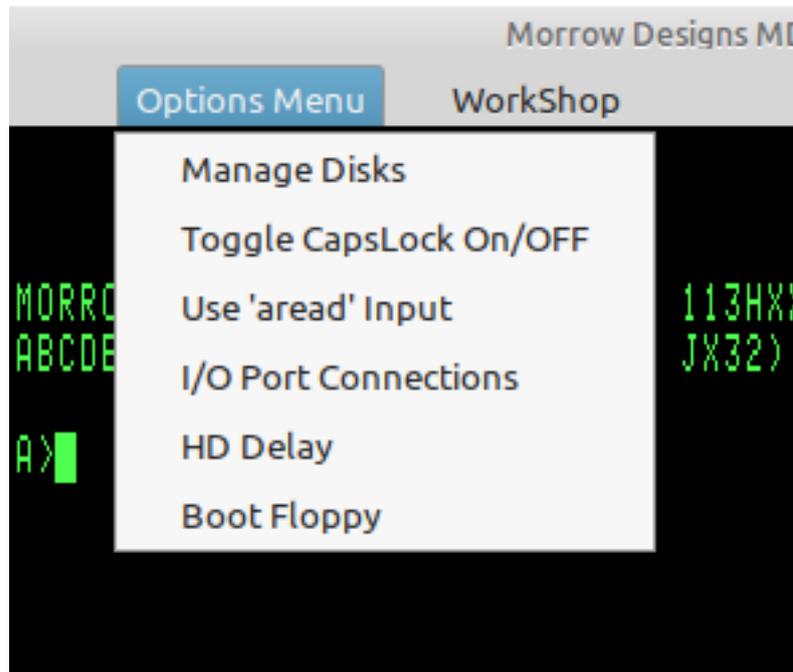


Fig. 6. The Options Menu

### 3.1 Disk Management.

The Disk Management menu item allows the user to 'eject' floppies and hard drives from the Emulator. The first displayed window shows what floppy disks happen to be 'inserted' in Floppy 1 or in Floppy 2. It also shows which hard drives were installed when the Emulator was booted.

Each disk-drive has two buttons: a 'Change' button which will install a different floppy-image or hard-disk image. And an 'Eject' button which removes any image-file which was previously installed.

If the 'Change' button is hit, a file-chooser dialog window opens and allows the user to browse through the whole file-system looking for a floppy-disk image to install. Once the file is selected, hit the 'Select' button to confirm your choice. The file-chooser window will close, the floppy-image is 'inserted' into the selected floppy-drive and is then ready for use.

The directory which the floppy-image came from will be used as the default disk directory in future disk-image searches. For this reason it is handy to store all your emulator floppy and hard-drive image-files in one or two directories.

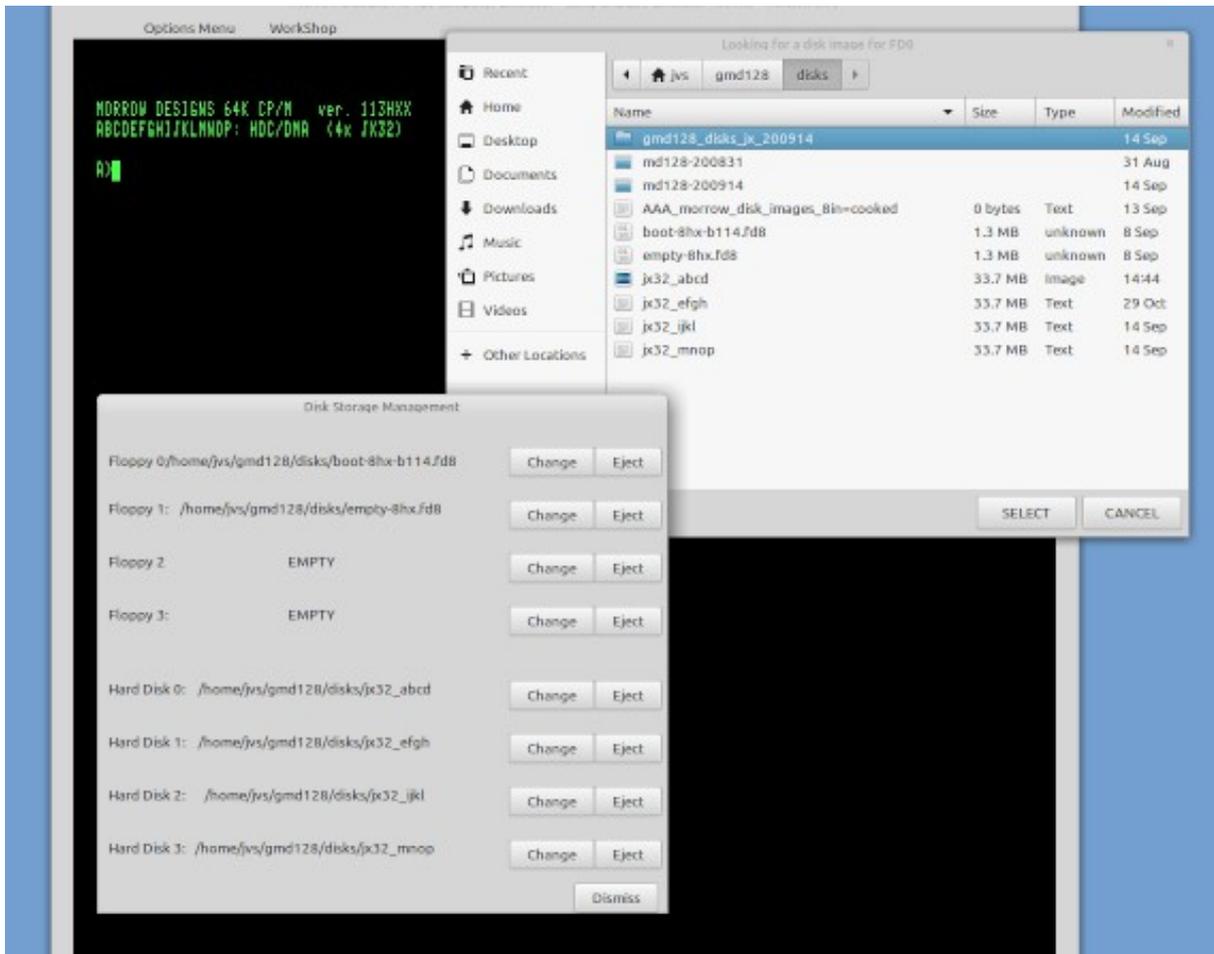


Fig. 7. Disk Selection Pop-Ups

### 3.2 Toggle Capslock ON and OFF

Many of the older Operating Systems will not recognise the use of lower-case characters. While one can use the actual Caps Lock Key to turn on the CapsLock, it would also turn on upper-case for the host Operating System as well. This can be a nuisance.

North Star DOS only understands uppercase commands, so it's necessary to toggle Capslock ON when using DOS. CP/M automatically converts command-line lowercase to uppercase anyway, so the Capslock setting can be set to personal preference.

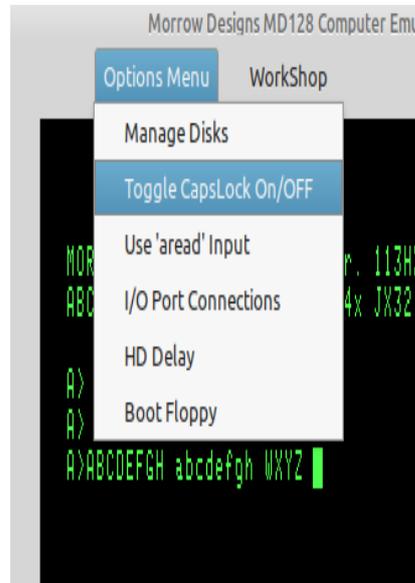


Fig 8. Capslock Toggled ON/OFF

In the screenshot above, Capslock starts out as being ON, showing the 'ABCDEFGH' in uppercase. Then Capslock is toggled to OFF, as shown in the Status Window, with the next set of characters being lowercase 'abcde fgh'. The Capslock is then toggled back ON, again showing in the Status Window, and the final 'WXYZ' is again uppercase

### 3.3 Use 'aread' Input.

Read in an ASCII file from disk instead of having to type it all in manually. The ASCII file is read in line-by-line until it has all been entered. The keyboard then waits for user input, as it does normally

The Input File is selected with a file-chooser window. It is read in immediately after being selected.

Files read in with 'aread' will be processed in exactly the same way as they would if typed in at the keyboard. Excessively long lines will be rejected by the command-line processor of some operating systems, WordStar can 'choke' temporarily because it is unable to keep up with the faster input, but it usually recovers well.

### 3.3 Toggle HD Delay ON/OFF

GMD128's 20 x speed emulation of the floppy disk drives and the hard disk drives is extremely fast! Even the 'slow' hard drive speed is very fast. It's unlikely that you will want to slow down the hard drive. The default speed is 'Fast'.

### 3.4 Allocate I/O Port Files

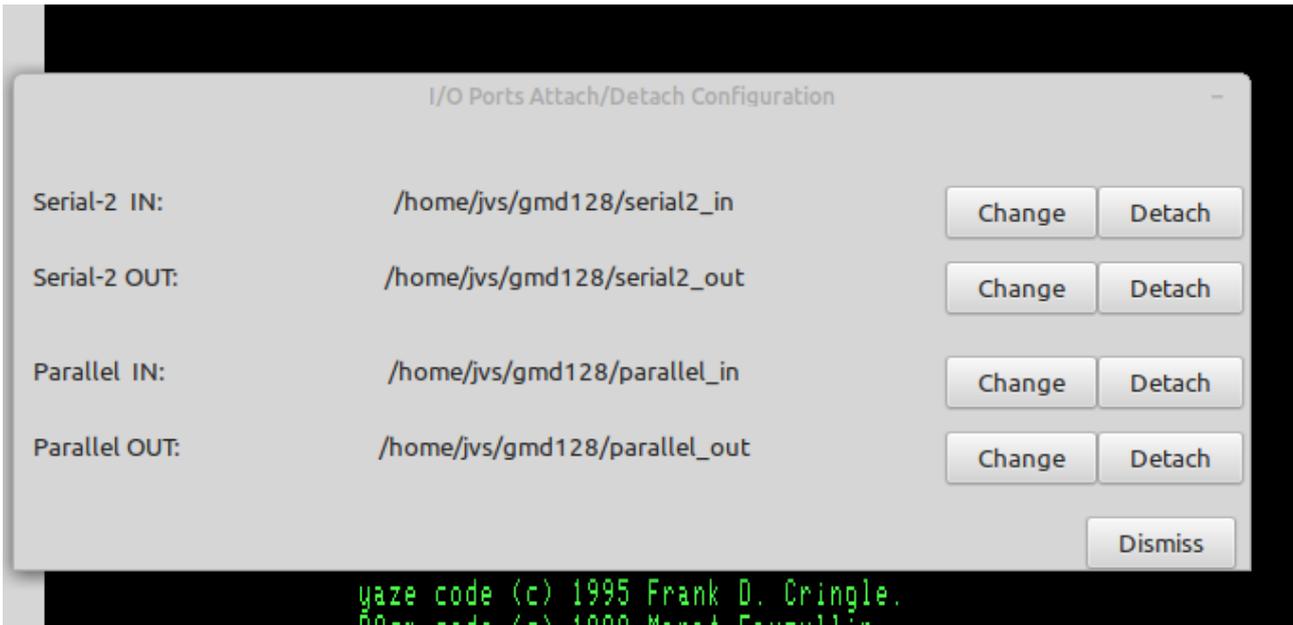


Fig 9. Allocating I/O Files to the gmd128 I/O Ports

Attach or detach a unix file to or from a gmd128 I/O Port. There is a parallel I/O port. And there is a serial I/O port. In unix, everything is a file so one unix file or pipe is attached to the second serial-in port, and another to the second serial-out port.

Example: The 'List' device is allocated to the parallel port. Anything sent to the 'List' device will therefore show up as data in the file attached to the parallel output port.

### 3.5 TEXT COLOR OF THE EMULATOR OUTPUT

A selection of colors is available for the screen display. As this is pretty much a 'set and forget forever' option, it was decided against having a color-selection window as one of the 'Options Menu' items. To make a change it is simply a matter of selecting suitable values for the 24-bit RGB components, RED\_LEVEL, BLUE\_LEVEL, GREEN\_LEVEL in the 'gxe.h' file and recompiling. Some examples -

Green on Black: (as default)

RED_LEVEL	0x3F
GREEN_LEVEL	0xFF
BLUE_LEVEL	0x3F

Amber on Black:

RED_LEVEL	0xFF
GREEN_LEVEL	0xBF
BLUE_LEVEL	0x3F

Yellow on Black:

RED_LEVEL	0xFF
GREEN_LEVEL	0xFF
BLUE_LEVEL	0x3F

White on Black:

RED_LEVEL	0xFF
GREEN_LEVEL	0xFF
BLUE_LEVEL	0xFF

#### 4.0 GMD128 DEVELOPMENT ASSISTANCE

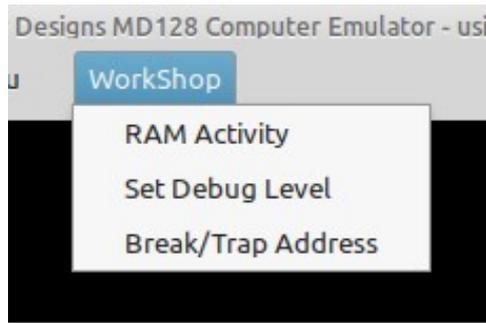


Fig 10. GMD128 Development menu: 'WorkShop'

#### 4.1 Display RAM in the Morrow gmd128 virtual machine.

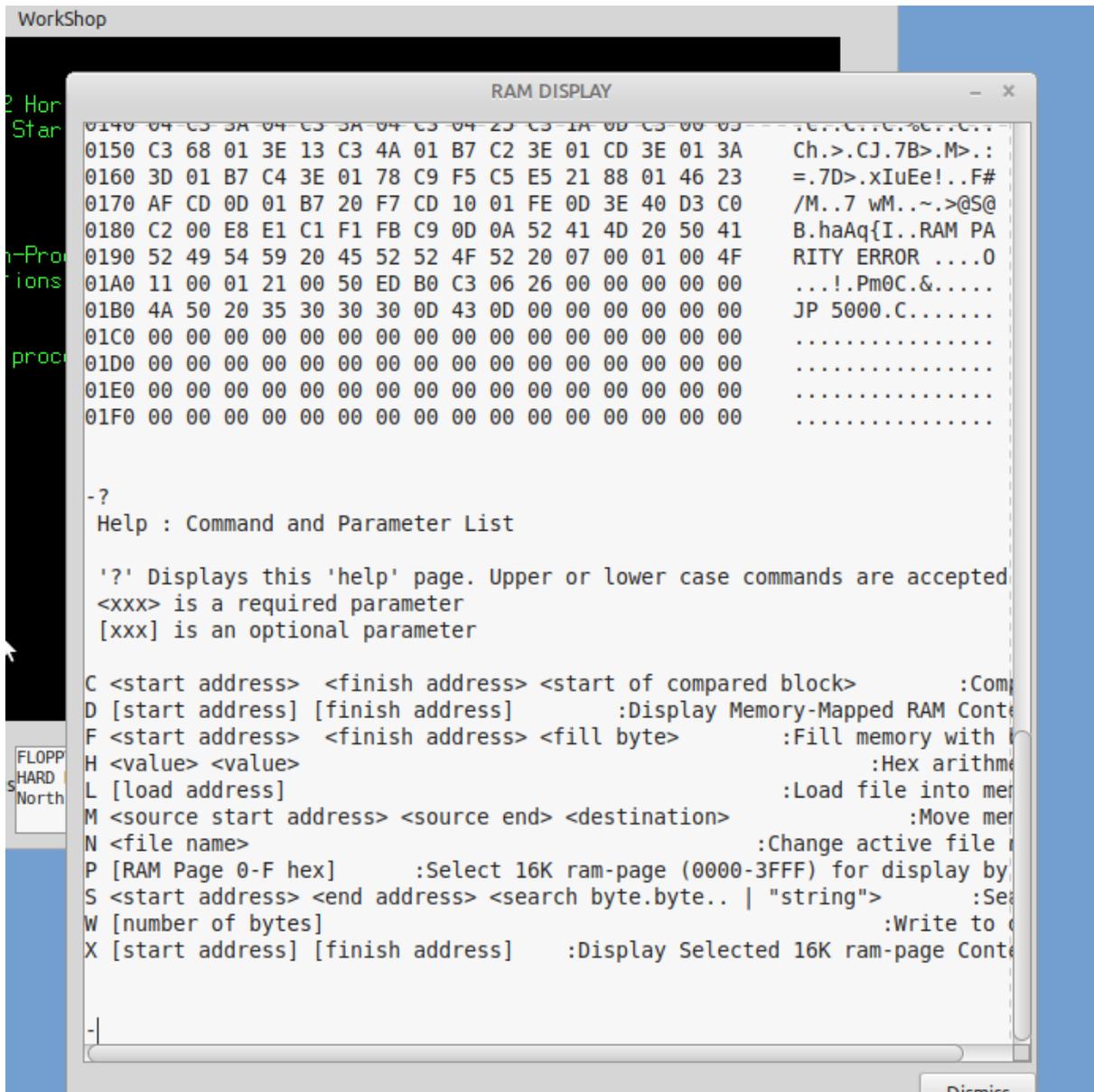


Fig 11. Display RAM Dialog

This subsystem has usage similar to CP/M 'DDT' or MSDOS 'DEBUG' Commands.

Upper or lower case commands are accepted  
 <xxx> is a required parameter, [xxx] is an optional parameter

### compare

*C* <start address> <finish address> <start of compared block>

**c 1a00 2000 2a00**

Compare two equal-length blocks of memory. Only the bytes which are different will be displayed with location and values.

### display

*D* [*start address*] [*finish address*]

**d 0 12FF**

Display the block of memory selected, showing bytes as hexadecimal and ASCII. If no start and end address specified, the command will continue for 100 H bytes from where it ended last.

### examine/substitute

*E* <start address>

**E 2CFF**

Examine/change values at memory locations. The operation is stopped when no new value is entered, just a plain 'enter'.

### fill

*F* <start address> <finish address> <fill byte>

**f 1000 2000 55**

Fill a block of memory with byte-value specified by <fill byte>.

### hex

*H* <value> <value>

**h 1267 abcd**

Hex arithmetic results of the addition of two values and the subtraction of the second value from the first value.

### load

*L* [*load address*]

**l 2a00**

Load the file (previously specified by the 'N' command) into memory. If a load-address is not specified the file will be loaded into location 0000 H.

### move

*M* <source start address> <source end> <destination>

**M 4d00 5000 6d00**

Move the block of memory specified by the block's start and end into memory beginning at the destination address.

### name

*N* <file name>

**N xtest.bin.bas**

Change active file-name which specifies which unix file will be used for 'load' and 'write' operations.

### quit

*Q*

Quit from the RAM display subsystem back to the emulator's control console.

## 4.2 Setting the Debug Parameters for the 'xlog' Debugging File Output

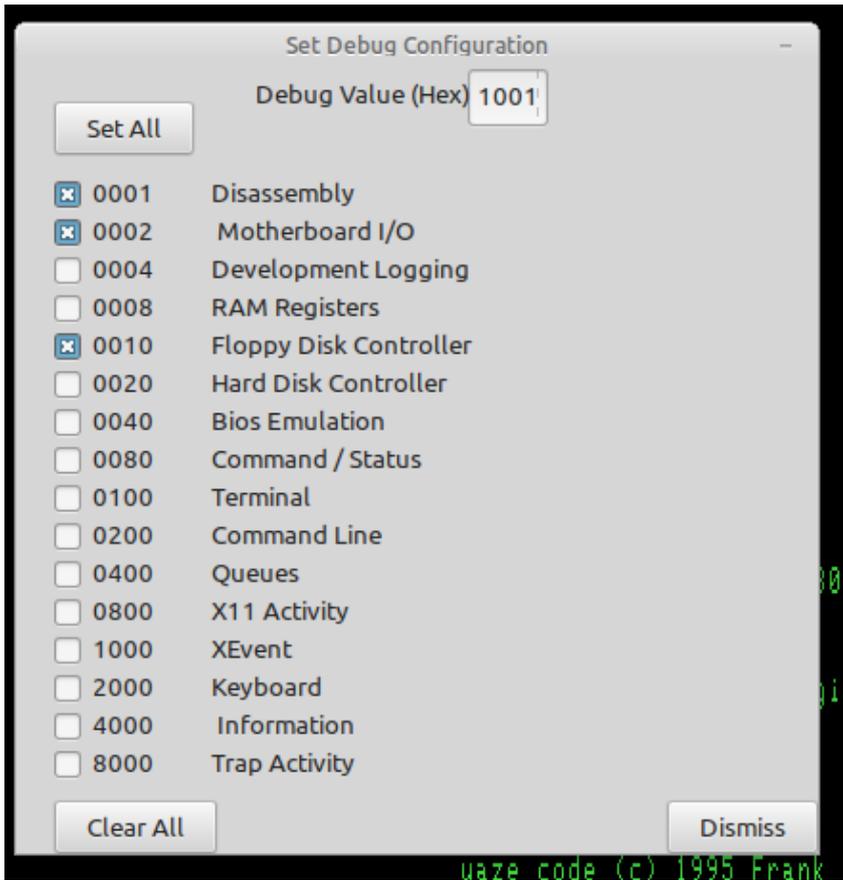


Fig 12. Setting Debug Logging Parameters

Depending on which items are selected for debug logging, a *lot* of logging output can be produced. Take care that your filesystem does not get over-filled.

## 4.3 Setting Execution Breakpoint Address, and Trap Address

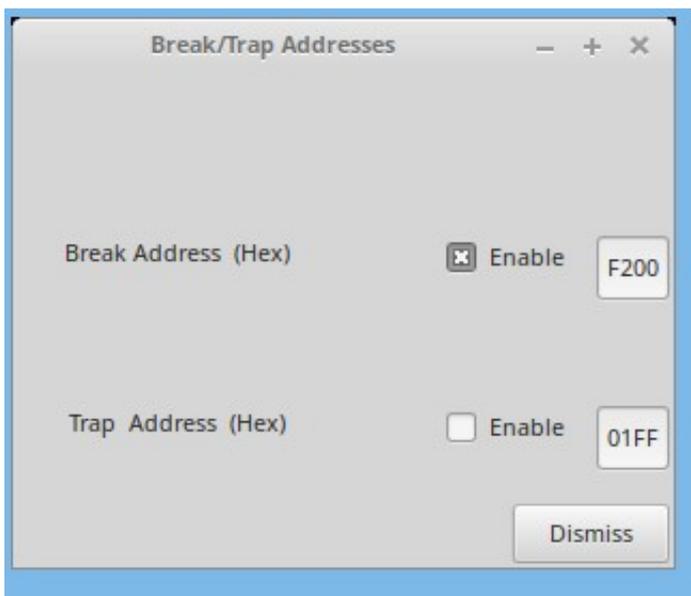


Fig 13. Enabling and Setting Break And Trap Addresses  
**break**

Set a breakpoint address to stop the emulator at a pre-specified address. This is equivalent to the "PAUSE" button, but it occurs at a desired execution address. The contents of the RAM can then be examined by using the Ram Display functions. Hitting the 'go' button will resume execution from that breakpoint address and it will continue until that breakpoint address is again reached, unless the breakpoint is disabled while execution is stopped.

### **trap**

Set a trap address to stop the emulator, perform a user-specified unix operation, return to the emulator and continue.

A dummy 'trap' function is included in the emulator source (trap.c) which merely prints the trap address and the register values. The trap function could be used to access parts of the host unix system or perform any other required operation.

Both the 'break' and 'trap' functions are enabled and disabled by the Check Buttons associated.

### **4.4 Log the debug information to Unix Disk File.**

Automatically sends debugging/information output to the 'xlog' unix file. Take care, because the quantity of information sent to the log file can reach the maximum size (2 Gig in 32-bit systems, whole disk or whole filesystem in 64-bit systems) within a fairly short time.

Unless you're doing development on the GMD128 Emulator itself, it probably will not be useful to use any debug logging at all.

### **4.5 Log the Screen Output to Unix Disk File.**

Automatically sends all ASCII screen text output to the 'screenlog' unix file. This can be handy to refer to if text output scrolls off the top of the screen before you can read it.

## 5. HELPER PROGRAMS

### 5.1 backup.gmd128

Run **backup.gmd128** from the work directory. This will look in the **disks** subdirectory for the four jx32 hard drive images (jx32\_abcd.img, jx32\_efgh.img, jx32\_ijkl.img, jx32\_mnop.img) and extract the individual files on the CP/M disk drives into directories designated A, B, C, ..... O, P. Each time the utility is run, a complete set of backup drives is produced and placed into a folder named **gmd128-<date of backup>** thus **gmd128-200914** or **gmd128-201130** and so forth

### 5.2 jx32\_sysgen

**jx32\_sysgen** is used to transfer the system boot track from one hard drive image file to another.

JX32-SYSGEN

Installs a bootable system track on a JX32 hard drive. The system may be copied from a hard drive which already contains a bootable system track. Otherwise this program will supply a suitable bootable system.

Enter SOURCE hard drive filename or else 'Enter' to install the default system : <ENTER KEY>

Using default version of boot system

If instead of just hitting the 'Enter' key, a hard drive image filename is given, the boot track will be taken from that hard disk image;

Enter SOURCE hard drive filename or else 'Enter' to install the default system : disks/jx32\_abcd.img

Getting system track from hard drive "disks/jx32\_abcd.img"

Having obtained the boot track, now give the DESTINATION hard drive image filename:

Enter DESTINATION hard drive filename or else 'Enter' to exit this program : disks/jx32\_efgh.img

Putting system track on hard drive "disks/jx32\_efgh.img"

Enter DESTINATION hard drive filename or else 'Enter' to exit this program :

After writing the boot track to the destination hard drive image, the program will request more destination disks. If you don't want to write to any other disk drives, just hit the 'Enter' key to finish.

### 5.3 **mkmd128floppy**

**mkmd128floppy** can generate a new blank floppy diskimage. Though I admit I find it easier to just copy a blank floppy image using the Linux **cp** utility.

```
MD11 Virtual Floppy Disk Maker and Formatter
(c) Jack Strangio 2014
```

```
This program prepares 8" and 5" Virtual Floppy Disk Files
```

```
The floppies can be formatted Double-Density containing 16 512-byte
or 8 1024-byte sectors per track, or Single-Density containing 26 128-byte
sectors per track. Either a single-side or both sides of the disk
can be formatted.
```

```
Is this a 5" or an 8" disk? g
Is this a Double-Density Disk? y
Is this a Double-Sided Disk? y
 128-byte (A), 512-byte (B), or 1024-byte (C) sectors? B
Sector Type = B, 16 512-byte sectors. track_code = 90. 77 tracks
```

```
Input disk name (omitting '.fd-type' suffix): mynewfloppy
Formatting disk: "mynewfloppy.fd8"
```

### 5.4 **jdz80** (Z80 disassembler)

**jdz80** is a slightly improved version of Marat Fayzullin's 1999 DAsm, in which relative jump destination addresses are calculated and displayed rather than just displaying the relative jump offsets.

### 5.5 **cpmtools**

Life is simpler with cpmtools-2.7 (or later) which can be obtained from most linux repositories. This set of utilities can be used to copy files directly between CP/M disk-images in the .fd8 and JX32 formats and the unix/linux file space. It will be necessary to add the disk definitions specified in the **gmd128\_diskdefs** file to the cpmtools config-file **diskdefs** which is usually at /etc/cpmtools/diskdefs.

The added disk-definitions will enable cpmtools to understand the GMD128 CP/M disk formats, both the floppy-disk images and the larger CP/M Virtual Disk Images on the hard disk.

The utilities in cpmtools include:

```
cpmls    list files in the North Star CP/M disk-image
cpmcp    copy files to and from the North Star CP/M disk-image
cpmrm    delete files from the North Star CP/M disk image
mkfs.cpm prepare stub disk for CP/M. In my experience, this does not work properly.
          Instead, use mkmd128floppy to produce a floppy disk then FORMAT it for CP/M.
```

### 5.6 **screenlog**

**screenlog** is not a tool as such but a record of GMD128's screen output.

### 5.7 **xlog**

**xlog** is not a tool but is a record of all debugging information. Can make very large log files.

## 6.1 OTHER FILES REQUIRED

Various floppy-disk image files:

These are available from various sources on the Internet.

## 6.2 COMPILING LIBRARIES REQUIRED

The linux libraries required are GTK+ version 3

## 6.3 VARIOUS USEFUL MANUALS

Most of the manuals are available from <https://itelsoft.com.au>.

Probably the most useful are:

This gmd128 User Guide  
CPM 2.2 Manual

These are all included in the 'documentation' directory

## 6.4 BUGS

I feel I have got many bugs out, which makes GMD128 very usable. But there are still a few to go, apart from the things that could be done to make GMD128 not quite so rough-edged. It certainly is not yet anywhere near as elegant as I would like, and the fault-lines between the several programs that GMD128 is based upon are still very visible. Please inform me of any bugs that you discover. Email me at: [jackstrangio@yahoo.com](mailto:jackstrangio@yahoo.com)

## 6.5 AUTHOR and SUPPORT

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## APPENDIX B. MORROW HARD DISKS WITH MULTIPLE PARTITIONS

### PHYSICAL FORMAT OF MORROW HARD DRIVES:

Each track contains nine 1024-byte sectors.  
Each cylinder contains eight tracks (8 heads).

Eight tracks will give (8x9) 1024-byte sectors per cylinder, making a total of 72 KB per cylinder.

### HARD DISKS HOLDING 7 x 4MB CP/M DRIVES:

For 4MB CP/M drives (4096k) we need  $4096/72 = 57$  cylinders  
 $57 \text{ cylinders} \times 7 \text{ drives (or partitions)} = 399 \text{ cylinders} + 1 \text{ system cylinder} = 400 \text{ cylinders}$

### HARD DISKS HOLDING 4 x 8MB CP/M DRIVES (JX\_32\_Drives):

For 8MB disks (8192k) we need 114 cylinders  
in a 32MB disk we need  $(4 \times 114) + 1 \text{ system cylinder} = 457 \text{ cylinders}$

### BIOS Version B113 PARAMETERS

Standard sectors (128-byte sectors) per cylinder =  $(72 \times 8) = 576$  sectors

Bad sector map at 4800 Hex from beginning of disk image in sector 0018 [0012 Hex] which is the first sector of track 2, on cylinder 0.

The System Track(s) starts on Track 0, on Cylinder 0. The System CP/M BIOS version B113 expects the HDC-DMA hard disk controller to be used

### Bios Version B114 PARAMETERS

CP/M BIOS Version B114 boots from an 8-inch floppy disk in floppy drive A: The BIOS will access two floppy drives and two JX\_32 hard drives. This BIOS uses both the Disk Jockey DJ-DMA floppy disk controller and the Morrow HDC-DMA hard disk controller. This BIOS is not as useful as the B113 BIOS which gives access to four JX\_32 hard drives. It also needs more work to be fully functional.